目 次 Contents

《船舶工程》2018年 第40卷 第11期

高雄子

专题: 船舶智能制造

智慧船厂概念模型研究

Research on Conceptual Model of Intelligent Shipyard 林 焰, 衣正尧, 李玉平, 纪卓尚 (1)

大型船舶平面分段智能车间的物流系统

Logistics System of Intelligent Workshop for Large Ship Flat Section
陈卫彬,郑志军,富 威,崔运山,肖凯元,马 岩(7)

船体小组立特征提取的机器视觉方法与实现 Methodology and Implementation of Machine Vision for Ship Small Assembly Feature Detection 倪崇本,储云泽,丁金鸿,陈 哲 (12)

船舶平面分段流水线模糊调度系统开发 Development of Ship Plane Segmented Line Fuzzy Scheduling System 兰宏凯,杨 志,柳存根,张水明 (18)

基于数据驱动的船体板件数控等离子切割精度控制 Precision Control of NC Plasma Cutting for Hull Plates Based on Data Driven 王 灿, 刘畅辉, 刘建峰, 孙建志, 张延松 (23)

船舶原理、船舶设计与船舶结构

数值模拟在船型方案优选中的应用
Application of Numerical Simulation on Selection of
Hull Line Optimization Schemes
杨 帆,董国祥,周红鹰,陈 灏(27)

棱形独立舱液化气船支承结构的局部强度研究 Study on Local Strength of Supports for Liquefied Gas Carrier with Independent Prismatic Tanks 郑文青,张玉奎,曾 佳(33)

30 万吨 FPSO 生活楼设计过程中的振动控制 Vibration Control during Design Procedure of 300 000 DWT FPSO Accommodation Area 张启鹏,成 磊,张 伟,项国林(39)

船舶机械

导管螺旋桨水动力学性能的影响因素
Influencing Factors of Hydrodynamic Performance of Ducted Propeller
宋 科,王文全, 闫 妍 (43)

基于分块结构网格的泵喷推进器敞水性能模拟 Simulation of Open Performance of Pumpjet Propeller Based on Block Structured Mesh 张 凯,叶金铭,于安斌(49) 盤舶低速柴油机推进轴系扭转振动研究 Stidy on Torsional Vibration of Propulsion Shafting for Low Speed Marine Diesel Engine 主 欢,肖能齐,薛海龙,乔红字(55)

二冲程柴油机扫气过程数值模拟分析 Numerical Simulation Analysis on Scavenging Processes of Two-Stroke Diesel Engine 赵 峰,于洪亮,段树林(61)

海上运动补偿混联舷桥的机构学建模 Mechanism Modeling of Sea Motion Compensated Hybrid Gangway 李二伟,赵铁石,王 唱,王文超,边 辉(66)

国外海上补给关键技术的发展 Development of Underway Replenishment Technology 崔 戈 (73)

船舶电气、导航、观通设备及自动控制

船用直流综合电力推进系统短路电流计算方法
Short Circuit Current Calculation Method of Marine DC Integrated
Power Propulsion System
张元玮,王良秀,胡 斌,王 乐,付文秀(77)

金属转轴无线感应供电系统传输功率分析与结构优化 Transmission Power Analysis and Structure Optimization of Wireless Induction Power Supply System on Metal Shaft 戴 明,王佩君,齐红丽,吉小军(83)

基于 GPS 和 BDS 的舰员落水报警定位系统设计 Design of Shipman Overboard Alarm and Positioning System Based on GPS and BDS 朱 炜,张 磊,郭 航(89)

深海装备及技术

基于载人潜水器的深海敷缆运动仿真 Motion Simulation of Deep-sea Cable-laying Based on Manned Submarine 姚晨佼,许可,范华涛,赵国良(94)

"十"字形矢量推进系统的设计 Design of Cruciform Vector Propulsion System 武建国,王昌强,王晓鸣,张敏革,林兴华(100)

基于 ADAMS 的水下扩展机构动力学仿真
Dynamic Simulation of Underwater Expansion Mechanism
Based on ADAMS
赖 慧, 杜向党, 安 徽(107)

行业新闻

NEWS

DNV GL 助力海德威 获 USCG 型式认可证书

(N1)

专题跟踪

技术新闻

全球首艘智能 VLOC 交付

(N4)

技术跟踪

数控等离子切割技术

(N6)

机器视觉系统

(N9)

技术规范

自主货物运输船舶指南 (2018)

(N11)



CONFIDENCE TO GO WHEREVER THE JOB TAKES YO

Simrad R5000 systems are available to meet the radar carriage requirements for CAT 1 (H), CAT 2 (H), SOLAS vessels.

A modular design makes it easy to create systems for commercial vessels of any size and type, from single-radar installations to fully networked multiradar and multi-station solutions.

SIMRAD°

www.navico.com/commercial