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Research Papers

Application of Combined Feedforward and Feedback Controller With Shaped Input to Benchmark Problem

Young Joo Shin and Peter H. Meckl

J. Dyn. Sys., Meas., Control. 2010;132(2):021001-021001-8. doi:10.1115/1.4000651.

Parameter Reduction in Estimated Model Sets for Robust Control

Ryozo Nagamune and Jongeun Choi

J. Dyn. Sys., Meas., Control. 2010;132(2):021002-021002-10. doi:10.1115/1.4000661.

Modeling, Analysis, and Optimal Design of the Automotive Transmission Ball Capsule System

Xingyong Song, Mohd Azrin Mohd Zulkefli, Zongxuan Sun and Hsu-Chiang Miao

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Application of dc Servomotor on Airflow Measurement

Thananchai Leephakpreeda

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Robust Control Synthesis Techniques for Multirate and Multisensing Track-Following Servo Systems in Hard Disk Drives

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On the Transient of Pressure Waves in Ducts for Systems Operating in Industrial Automation

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A Dynamic Model of an Electropneumatic Valve Actuator for Internal Combustion Engines

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Stabilization of Unstable Fixed Points of Fractional-Order Systems by Fractional-Order Linear Controllers and Its Applications in Suppression of Chaotic

Oscillations

Mohammad Saleh Tavazoei and Mohammad Haeri

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Adaptive Neuro-Fuzzy Inference System in Fuzzy Measurement to Track Association

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Physics Based Control Oriented Model for HCCI Combustion Timing

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Design and Testing of a Nanometer Positioning System

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A QFT Framework for Antiwindup Control Systems Design

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Modified Maximum Entropy Fuzzy Data Association Filter

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Technical Briefs

Identification of a Variable Mass Underwater Vehicle Via Volterra Neural Network

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Computationally Efficient Multisensor Fusion Estimation Algorithms

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Online Identification and Stochastic Control for Autonomous Internal Combustion Engines

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Minimizing Residual Vibration in Short-Maneuver Pulse-Width Control

Keith W. Buffinton, Katie L. Hoffman and Martin C. Berg

