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Research Papers

Extended Angular-Velocity Vold–Kalman Order Tracking

Min-Chun Pan and Cheng-Xue Wu

J. Dyn. Sys., Meas., Control. 2010;132(3):031001-031001-11. doi:10.1115/1.4001326.

Motion Control of a Container With Slosh: Constrained Sliding Mode Approach

Hanz Richter

J. Dyn. Sys., Meas., Control. 2010;132(3):031002-031002-10. doi:10.1115/1.4001329.

Robust Control and Time-Domain Specifications for Systems of Delay Differential Equations via Eigenvalue Assignment

Sun Yi, Patrick W. Nelson and A. Galip Ulsoy

J. Dyn. Sys., Meas., Control. 2010;132(3):031003-031003-7. doi:10.1115/1.4001339.

Estimating Road Angles With the Knowledge of the Vehicle Yaw Angle

Ling-Yuan Hsu and Tsung-Lin Chen

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A Framework for Discrete-Time H₂ Preview Control

A. J. Hazell and D. J. N. Limebeer

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Automatic In-Process Chatter Avoidance in the High-Speed Milling Process

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Repeatable Redundant Manipulator Control Using Nullspace Quasivelocities

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Position-Error Based Schemes for Bilateral Teleoperation With Time Delay: Theory and Experiments

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Efficient Operation of Air-Side Economizer Using Extremum Seeking Control

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Minimax State/Residual-Energy Constrained Shapers for Flexible Structures: Linear Programming Approach

Matthew Vossler and Tarunraj Singh

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Technology Reviews

Nonlinear Dynamics and Its Applications in Micro- and Nanoresonators

Jeffrey F. Rhoads, Steven W. Shaw and Kimberly L. Turner

J. Dyn. Sys., Meas., Control. 2010;132(3):034001-034001-14. doi:10.1115/1.4001333.

Technical Briefs

On Transient Improvement of Variable Structure Controlled Systems Using Multimodel Switching

Mehmet Akar

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Chatter Detection in Machining Using Nonlinear Energy Operator

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Design of Gain-Scheduled Strictly Positive Real Controllers Using Numerical Optimization for Flexible Robotic Systems

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Stochastic Finite-Time Stabilization for Uncertain Jump Systems via State Feedback

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Brachistochrone on a 1D Curved Surface Using Optimal Control

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